

# Deskstar 14GXP DTTA-371010, DTTA-371290, DTTA-371440

IBM OEM has introduced a new range of 7,200 Rpm disk drives for the desktop personal computer marketplace.

Available in three capacity points with AT interface, the drive provides excellent performance and reliability.

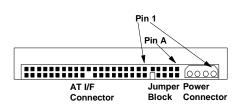
# **Applications**

Performance Desktop personal computers Entry servers Entry workstations

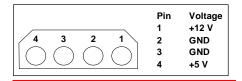


Features	Benefits
<b>10.1GB</b> , <b>12.9GB</b> , <b>14.4GB</b> at 512 bytes/sector	Range of high capacities to meet the need for demanding storage requirements
PIO and DMA data transfer modes PIO Mode 4 rates up to 16.6MB/sec Ultra DMA/33 rates up to 33.3MB/sec	Fast interface data rates
Average seek time 9.1ms (Read) 9.5ms(Write) 7200 RPM	Fast access to data
464KB segmented sector buffer	Fast data retrieval in single and multitasking applications
Industry standard mounting The drive can be mounted with any of its six surfaces facing down	Ease of installation
Advanced ECC on the fly (EOF)	Improved data throughput
CHS and LBA addressing modes	Flexibility to support most appropriate addressing
Power saving modes	Reduced power consumption
Robust design for EMC/RFI	Easy integration across multiple platforms
GMR (Giant Magneto Resistive) head technology	High areal density, low component count
No ID sector format PRML Data Channel	More data stored per track, increased sustained data transfer rate
S.M.A.R.T. function support	High reliability and availability
Security function support	Password protection for sensitive data

#### **Connectors**



The DC power connector is designed to mate with AMP part 1-480424 (using AMP pins P/N 350078-4). Equivalent connectors may be used. Pin assignments are shown below, viewed from the end of the drive.



#### AT I/F Connector

The drive uses single-ended drivers and receivers. The connector is designed to mate with 3M part 3417-7000 or equivalent.

**Note:** It is intended that the hard disk should only be in electrical contact with the chassis of the PC at a designated set of mounting holes. Other electrical contact may degrade error rate performance. As a result, it is recommended that there should be no metal contact to the hard disk drive except at the mounting holes or the side rails into which the mounting holes are tapped.

#### Jumper Block

# **Jumper Settings**

Jumpers may be fitted to select the following options:-

# head logical architecture

MASTER active	<b>Pin Numbers</b> A-B and G-H
SLAVE active	A-B and C-D
Cable sel	A-B and E-F
SLAVE Present	E-F and G-H
Reserved	1

# 15 head logical architecture

#### **Pin Numbers**

MASTER active	A-C and G-H
SLAVE active	A-C
Cable sel	A-C and E-F
SLAVE Present	A-C, E-F and G-H
Reserved	I

All other jumper setting patterns are reserved. **DO NOT MAKE OTHER SETTINGS!** 



#### Shipping Default Settings

MASTER is set to on.

PACKAGING: The drive must be protected against Electrostatic Discharge especially when being handled. The safest way to avoid damage is to put the drive in an anti static bag before ESD wrist straps etc. are removed.

Drives should only be shipped in approved containers. Severe damage can be caused to the drive if the packaging does not adequately protect against the shock levels induced when a box is dropped. Consult your IBM marketing representative if you do not have an approved shipping container.

# **Operating Environment**

# **Operating Conditions**

Temperature 5° to 55°C\*
Relative Humidity 8 to 90%

non-condensing 29.4°C

Maximum Wet Bulb Temperature

non-condensing

Maximum

16

Temperature Gradient 15°C/Hour Altitude -300 to 3048m

#### **Non Operating Conditions**

Temperature -40° to 65°C Relative Humidity 5 to 95%

non-condensing

Maximum Wet Bulb 35°C

Temperature non-condensing

Maximum

Temperature Gradient 15°C/Hour
Altitude -300 to 12,000m

**Note:** \* The system is responsible for providing sufficient air movement to maintain surface temperature below 60°C at the center of the top cover of the drive.

# **Operating Shock**

The hard disk drive meets the following criteria while operating in respective conditions described below. There must be a delay between shock pulses, long enough to allow the drive to complete all necessary error recovery procedure.

No data loss 10G, 11ms half-sine

shock pulse

#### Non-Operating Shock

The drive withstands a 75G half-sine wave shock pulse of 11ms duration on six sides without damage or degradation of performance when heads are parked. (When power is not applied to the unit the heads are automatically located in the parked position). The above specification is for shocks applied in each direction of the drives three mutually perpendicular axes, one axis at a time.

#### Operating Vibration

Due to the complexity of this subject we recommend that users contact the IBM technical support group representative to discuss how to perform the necessary measurements if they believe this to be an area which requires evaluation

.

#### **DC Power Requirements**

The following voltage specifications apply at the drive power connector. Damage to the drive electronics may result if the power supply cable is connected or disconnected while power is being applied to the drive (Hot plug/unplug is not allowed). There is no special power on/off sequencing required.

# Input Voltage

- +5 Volts Supply 5V(+/-5% during run and spin up)<sup>1</sup> +12 Volts Supply 12V(+10%,-8% during run and spin up)<sup>2</sup>
- To avoid damage to the file electronics 5V power supply voltage spikes must
- <sup>2</sup> To avoid damage to the file electronics 12V, power supply voltage spikes must not exceed 15V.

#### **Power Supply Current**

not exceed 7V.

(All values in Amps.)		+12 volts Pop Mean
Idle average	0.29	0.45
Idle ripple (peak to peak	s) 0.25	0.70
Seek peak <sup>1</sup>	0.55	1.70
Seek average <sup>1</sup>	0.33	0.70
Start up (max)	0.70	2.0
Random R/W peak <sup>2</sup>	0.80	0.75
Random R/W average <sup>2</sup>	0.42	0.65
Standby/Sleep average	0.15	0.005

- <sup>1</sup> Random Seeks at 40% duty cycle.
- <sup>2</sup> Seek duty = 30%, W/R duty = 45%, Idle duty = 25%.

Power Supply Generated Ripple as seen at file power connector.

	Maximum	Notes
+5V DC	100mV pp	0-10 MHz
+12V DC	150mV pp	0-10 MHz

#### **DC Power Requirements**

During file start up and seeking, 12 volt ripple is generated by the file (referred to asdynamic loading). If several files have their power daisy chained together then the power supply ripple plus other file's dynamic loading must remain within the regulation tolerance of +10/-8%. A common

supply with separate power leads to each file is a more desirable method of power distribution.

To prevent external electrical noise from interfering with the file's performance, the file must be held by four screws in a user system frame which has no electrical level difference at the four screws position, and has less than +/- 300 millivolts peak to peak level difference to the file power connector ground.

#### Cabling

The maximum cable length from the Host system to the drive, plus the circuit pattern length inside the Host systems, must not exceed 18 inches (45.7cm).

For higher data transfer application >8.3MB/sec, a consideration in system design is recommended to reduce cable noise and/or cross-talk, such as shorter cable, bus termination, shielded cable, etc.

#### Interface

The interface conforms to the working document of information technology - AT Attachment with Packet Interface Extension (ATA/ATAPI-4) Revision 16 dated 25th August 1997 with the following deviators.

#### **Check Power Mode**

CHECK POWER MODE command returns FFh to Sector Count Register when the device is in Idle mode. This command does not support 80h as the return value.

#### **Hard Reset**

Hard Reset response is identical to Soft Reset response with the following exception:

When drive is MASTER the DASP line is not checked and SLAVE presence is assumed to be unchanged. When drive is set as a SLAVE it will activate DASP line to indicate it is present.

# Electromagnetic Compatibility

The drive meets the following EMC requirements when installed in a suitable user system and exercised with a random accessing routine at maximum data rate:

United States Federal Communication Commission (FCC) Rules and Regulations Part 15, subject J -Computer Devices "Class B Limits".

European Economic Community (ECC) directive #76/889 related to the control of radio frequency interference and the Verband Deutscher Elektrotechniker (VDE) requirements of Germany (GOP).

Council Directive 89/336/EEC on the approximation of laws of the Member States relating to electromagnetic compatibility.

C-Tick Mark complies with Australian EMC standard, AS/NZS 3348:1995 CLASS-B..

# Interface

# Data Organization

Description	DTTA 371010	DTTA 371290	DTTA 371440
Physical Layout			
Label Capacity (MB)	10,100	12,900	14,400
Bytes per Sector	512	512	512
Sector per Track	165 - 264	165 - 264	165 - 264
No. of Heads	7	9	10
No. of Disks	4	5	5
Logical Layout <sup>1</sup>			
No. of Heads <sup>2</sup>	16 (15)	16 (15)	16 (15)
No. of Sectors/Track <sup>3</sup>	63	63	63
No. of Cylinders <sup>4</sup>	16,383	16,383	16,383
No. of Sectors <sup>5</sup>	19,746,720	25,385,472	28,229,040

Logical layout describes imaginary HDD parameters which are used to access customer data on the disk drive. Logical layout to physical layout (ie. actual Head, Sector translation) is done automatically in the HDD. Default setting can be obtained by issuing IDENTIFYING DRIVE command.

Bood Costors (rotry)

<sup>&</sup>lt;sup>4</sup> Value is reported in Word 1 of HDD IDENTIFY data. Value is reported in Word 60 & 61 of HDD IDENTIFY data

_			
Com	mano	l Desc	riptions

The following Commands are supported by the Drive:

2) u.o 2o.		
Commands	(Hex)	P
Check Power Mode	(E5)	3
Check Power Mode*	(98)	3
Executive Drive Diagnostics	(90)	3
Flush Cache	(E7)	3
Format Track	(50)	2
Identify Device	(EC)	1
Identify Drive DMA	(EE)	4
Idle	(E3)	3
Idle*	(97)	3
Idle Immediate	(E1)	3
Idle Immediate*	(95)	3
Initialise Drive Parameters	(91)	3
Red Buffer	(E4)	1
Read DMA (retry)	(C8)	4
Read DMA (no retry)	(C9)	4
Read DMA Queued	(C7)	5
Read Long (retry)	(22)	1
Read Long (no retry)	(23)	1
Read Multiple	(C4)	1
Read Native Max LBA/CYL	(F8)	+3

Read Sectors (retry)	(20)	1	
Read Sectors (no retry)	(21)	1	
Read Verify Sectors (retry)	(40)	3	
Read Verify Sectors (no retry)	(41)	3	
Recalibrate	(1X)	3	
Security Disable Password	(F6)	2	
Security Erase Prepare	(F3)	3	
Security Erase Unit	(F4)	2	
Security Freeze Lock	(F5)	3	
Security Set Password	(F1)	2	
Security Unlock	(F2)	2	
Seek	(7X)	3	
Service	(A2)	5	
Set Features	(EF)	3	
Set Max LBA/CYL	(F9)	3+	
Set Multiple	(C6)	3	
Sleep	(E6)	3	
Sleep*	(99)	3	
SMART Disable Operations	(BO)	3	
SMART Enable/Disable Attribute Autosave	(BO)	3	
SMART Enable Operations	(BO)	3	
SMART Execute Off-line Data Collection	(BO)	3	

SMART Read Attribute Values	(BO)	1
SMART Read Attribute Thresholds	(BO)	1
SMART Return Status	(BO)	3
SMART Save Attribute Values	(BO)	3
Standby	(E2)	3
Standby*	(96)	3
Standby Immediate	(EO)	3
Standby Immediate*	(94)	3
Write Buffer	(E8)	2
Write DMA (retry)	(CA)	4
Write DMA (no retry)	(CB)	4
Write DMA Queued	(CC)	5
Write Long (retry)	(32)	2
Write Long (no retry)	(33)	2
Write Multiple	(C5)	2
Write Sectors (retry)	(30)	2
Write Sectors (no retry)	(31)	2
Protocol		

# 1 PIO data IN command 2 PIO data OUT command 3 Non data command 4 DMA command + Vendor specific command

Vendor specific command Alternate command codes for previous defined commands

<sup>&</sup>lt;sup>2</sup> Bracketed values show alternate jumper selectable option. Value is reported in Word 3 of HDD IDENTIFY data.

<sup>&</sup>lt;sup>3</sup> Value is reported in Word 6 of HDD IDENTIFY data.

#### Registers (Primary Channel Addresses)

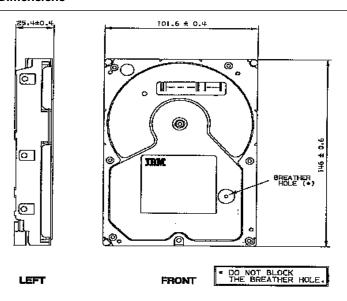
Address	Input Register	Output Register
1F0h	Data	Data
1F1h	Error	Features
1F2h	Sector Count	Sector Count
1F3h	Sector Number *LBA bits 0-7	Sector Number *LBA bits 0-7
1F4h	Cylinder Low *LBA bits 8-15	Cylinder Low *LBA bits 8-15
1F5h	Cylinder High *LBA bits 16-23	Cylinder High *LBA bits 16-23
1F6h	Drive/Head *LBA bits 24-27	Drive/Head *LBA bits 24-27
1F7h	Status	Command
3F6h	Alternate Status	Device Control
3F7h	Drive Address	Not Used

The host uses the register interface to communicate with the drive. The registers are accessed through the host port addresses shown. The host should not read or write any registers when the Status Register BSY bit = 1.

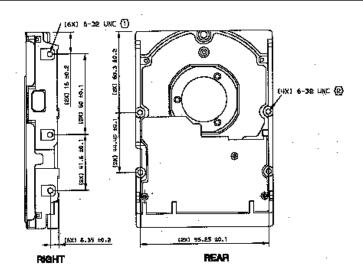
**Note:** \* Meaning of Register contents when LBA addressing mode used.

Mechanical Data		
Dimensions		
Height	25.4 +/- 0.4mm	
Width	101.6 +/- 0.4mm	
Length	146.0 +/- 0.6mm	
Weight	630g maximum	

# **Outline Dimensions**



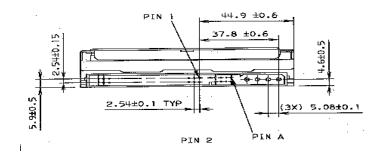
# **Mounting Holes**



The recommended mounting screw torque is 0.6-1.0(NM) (6-10[Kgf.cm)).

- <sup>1</sup> Max allowable penetration of noted screw to be 4.5mm
- <sup>2</sup> Max allowable penetration of noted screw to be 4.0mm.

#### **Connector Locations**





#### **IBM United Kingdom Limited**

PO Box 41 Portsmouth Hampshire PO6 3AU United Kingdom

Telephone: (44) 1705 561000

USA Headquarters: (408) 256-8000

Japan Headquarters: (81) 466-45-1384

Asia-Pacific Headquarters: (65) 320-1503

The IBM Storage home page can be found at

http://www.ibm.com/storage/hddtech

Registered in England: No. 741598

UK company-wide registration to ISO90001. Certificate number FM12587.

IBM is the registered trademark of International Business Machines Corporation.

AMP is a trademark of AMP Incorporated Molex is a trademark of Molex Incorporated DATA MATE is a trademark of AMP Incorporated

Other company, product and service names may be trademarks or service marks of others.

This data sheet is not a substitute for the full production specification, which should be used when detailed information is required.

Product Description data represents IBM's design objectives and is provided for comparative purposes; actual results may vary based on a variety of factors. This product data does not constitute a warranty. Questions regarding IBM's warranty terms or methodology used to derive this data should be referred to your IBM OEM representative. Data subject to change without notice.

Date: December 11, 1998

Spec. Revision 2.0

Produced by European SIT Lab.

© International Business Machines Corporation 1997.

Distributor: